

**CHAPTER 2**

**DIGITAL  
IMAGE TRANSFORM  
ALGORITHMS**

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## *Introduction*

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- ◆ Image transforms are represented by transform matrices  $\mathbf{A}$ :

$$\mathbf{X} = \mathbf{A}\mathbf{x}$$

where  $\mathbf{x}$  and  $\mathbf{X}$  are the original and transformed image respectively.

In most cases the transform matrices are *unitary*:

$$\mathbf{A}^{-1} = \mathbf{A}^{*T}$$

- ◆ The columns of  $\mathbf{A}^{*T}$  are the *basis vectors* of the transform and in 2-d transforms they correspond to *basis images*.

- ◆ The most popular image transforms are:

-  *Discrete Fourier Transform (DFT).*

-  *Discrete Cosine Transform (DCT).*

## *Two-dimensional discrete Fourier transform*

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Let  $\tilde{x}(n_1, n_2)$  be a 2-d rectangularly periodic sequence.  
Its periodicity is defined as:

$$\tilde{x}(n_1, n_2) = \tilde{x}(n_1 + N_1, n_2) = \tilde{x}(n_1, n_2 + N_2)$$

where  $N_1, N_2$  denote the horizontal and vertical periods.

The fundamental period of this sequence is the rectangle  $R_{N_1 N_2}$  having size  $N_1 \times N_2$ :

$$R_{N_1 N_2} = \{(n_1, n_2) : 0 \leq n_1 < N_1, 0 \leq n_2 < N_2\}$$

## *Two-dimensional discrete Fourier transform*

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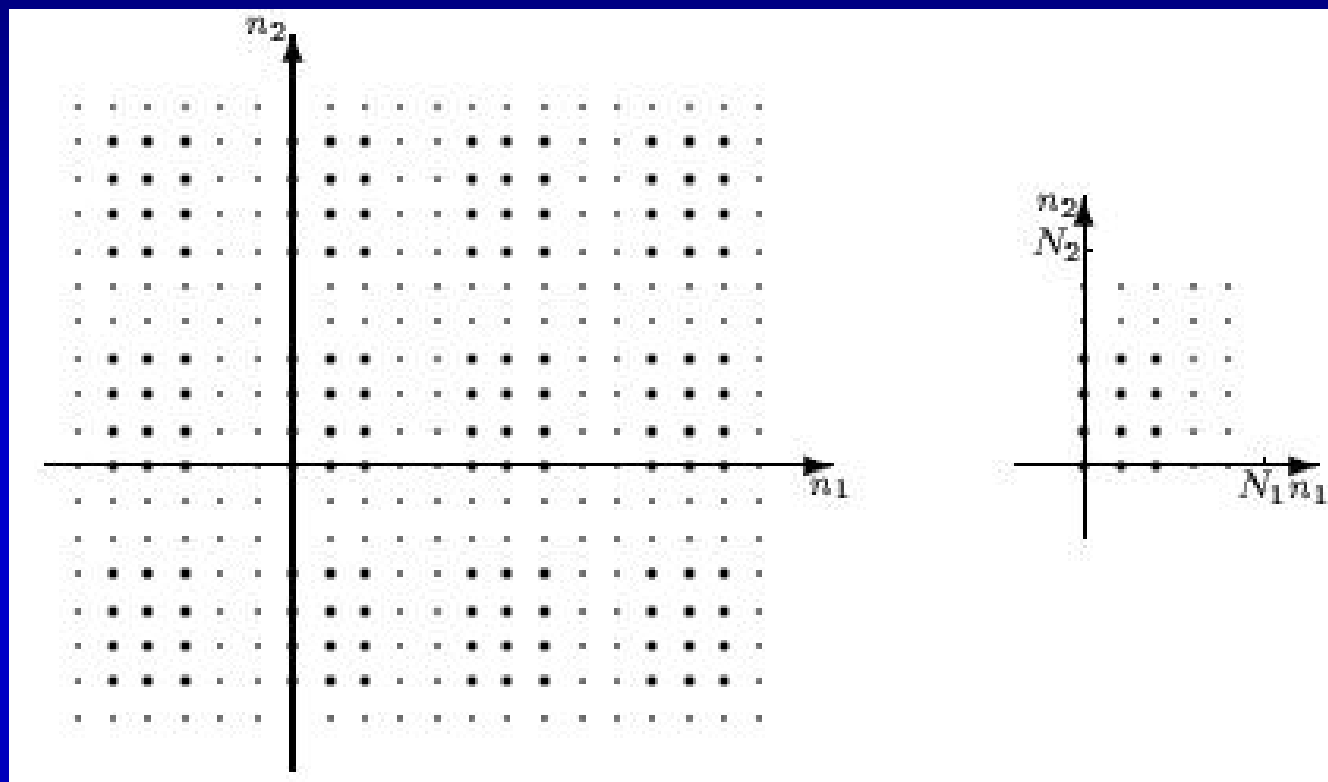


Figure 1: Rectangularly periodic sequence and its fundamental period.

## *Two-dimensional discrete Fourier transform*

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- ◆ A periodic sequence can be represented by a Fourier series.
- ◆ The 2-d DFS is used for the representation of a 2-d rectangularly periodic signal:

$$\tilde{x}(n_1, n_2) = \frac{1}{N_1 N_2} \sum_{k_1=0}^{N_1-1} \sum_{k_2=0}^{N_2-1} \tilde{X}(k_1, k_2) \exp\left(i \frac{2\pi n_1 k_1}{N_1} + i \frac{2\pi n_2 k_2}{N_2}\right)$$

- ◆ The Fourier series coefficients are :

$$\tilde{X}(k_1, k_2) = \sum_{n_1=0}^{N_1-1} \sum_{n_2=0}^{N_2-1} \tilde{x}(n_1, n_2) \exp\left(-i \frac{2\pi n_1 k_1}{N_1} - i \frac{2\pi n_2 k_2}{N_2}\right)$$

## *Two-dimensional discrete Fourier transform*

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◆ A discrete 2-d space-limited signal can be represented by DFT as:

$$X(k_1, k_2) = \sum_{n_1=0}^{N_1-1} \sum_{n_2=0}^{N_2-1} x(n_1, n_2) \exp \left( -i \frac{2\pi n_1 k_1}{N_1} - i \frac{2\pi n_2 k_2}{N_2} \right)$$

$$x(n_1, n_2) = \frac{1}{N_1 N_2} \sum_{k_1=0}^{N_1-1} \sum_{k_2=0}^{N_2-1} X(k_1, k_2) \exp \left( i \frac{2\pi n_1 k_1}{N_1} + i \frac{2\pi n_2 k_2}{N_2} \right)$$

## *Two-dimensional discrete Fourier transform*

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- ◆ Another commonly used form of the DFT is:

$$X(k_1, k_2) = \sum_{n_1=0}^{N_1-1} \sum_{n_2=0}^{N_2-1} x(n_1, n_2) W_{N_1}^{n_1 k_1} W_{N_2}^{n_2 k_2}$$

$$x(n_1, n_2) = \frac{1}{N_1 N_2} \sum_{k_1=0}^{N_1-1} \sum_{k_2=0}^{N_2-1} X(k_1, k_2) W_{N_1}^{-n_1 k_1} W_{N_2}^{-n_2 k_2}$$

$$\text{where: } W_{N_j} = \exp \left( -i \frac{2\pi}{N_j} \right) \quad j = 1, 2$$



## *Two-dimensional discrete Fourier transform*

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◆ The DFT is related to the Fourier transform of a discrete 2-d signal which is defined as:

$$X(\mathbf{w}_1, \mathbf{w}_2) = \sum_{n_1=-\infty}^{\infty} \sum_{n_2=-\infty}^{\infty} x(n_1, n_2) \exp(-i\mathbf{w}_1 n_1 - i\mathbf{w}_2 n_2)$$

$$x(n_1, n_2) = \frac{1}{4p^2} \int_{-p}^p \int_{-p}^p X(\mathbf{w}_1, \mathbf{w}_2) \exp(i\mathbf{w}_1 n_1 + i\mathbf{w}_2 n_2) d\mathbf{w}_1 d\mathbf{w}_2$$

The DFT coefficients are a sampled version of the 2-d FT of a discrete sequence:

$$X(k_1, k_2) = X(\mathbf{w}_1, \mathbf{w}_2) \Big|_{\mathbf{w}_1 = \frac{2\pi k_1}{N_1}, \mathbf{w}_2 = \frac{2\pi k_2}{N_2}}$$

over the unit bicircle  $z_1 = \exp(i\hat{u}_1)$ ,  $z_2 = \exp(i\hat{u}_2)$ .

## *Two-dimensional discrete Fourier transform*

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- ◆ The *circular convolution* of two signals can be computed by means of the *circular shift* of a signal.

### Circular Shift

$$y(n_1, n_2) = x(((n_1 + m_1))_{N_1}, ((n_2 + m_2))_{N_2})$$

$$((n))_N \stackrel{\Delta}{=} n \bmod N$$

### Circular Convolution

$$\begin{aligned} y(n_1, n_2) &\stackrel{\Delta}{=} x(n_1, n_2) \otimes \otimes h(n_1, n_2) = \\ &= \sum_{m_1=0}^{N_1-1} \sum_{m_2=0}^{N_2-1} x(m_1, m_2) h(((n_1 - m_1))_{N_1}, ((n_2 - m_2))_{N_2}) \end{aligned}$$

# *Two-dimensional discrete Fourier transform*

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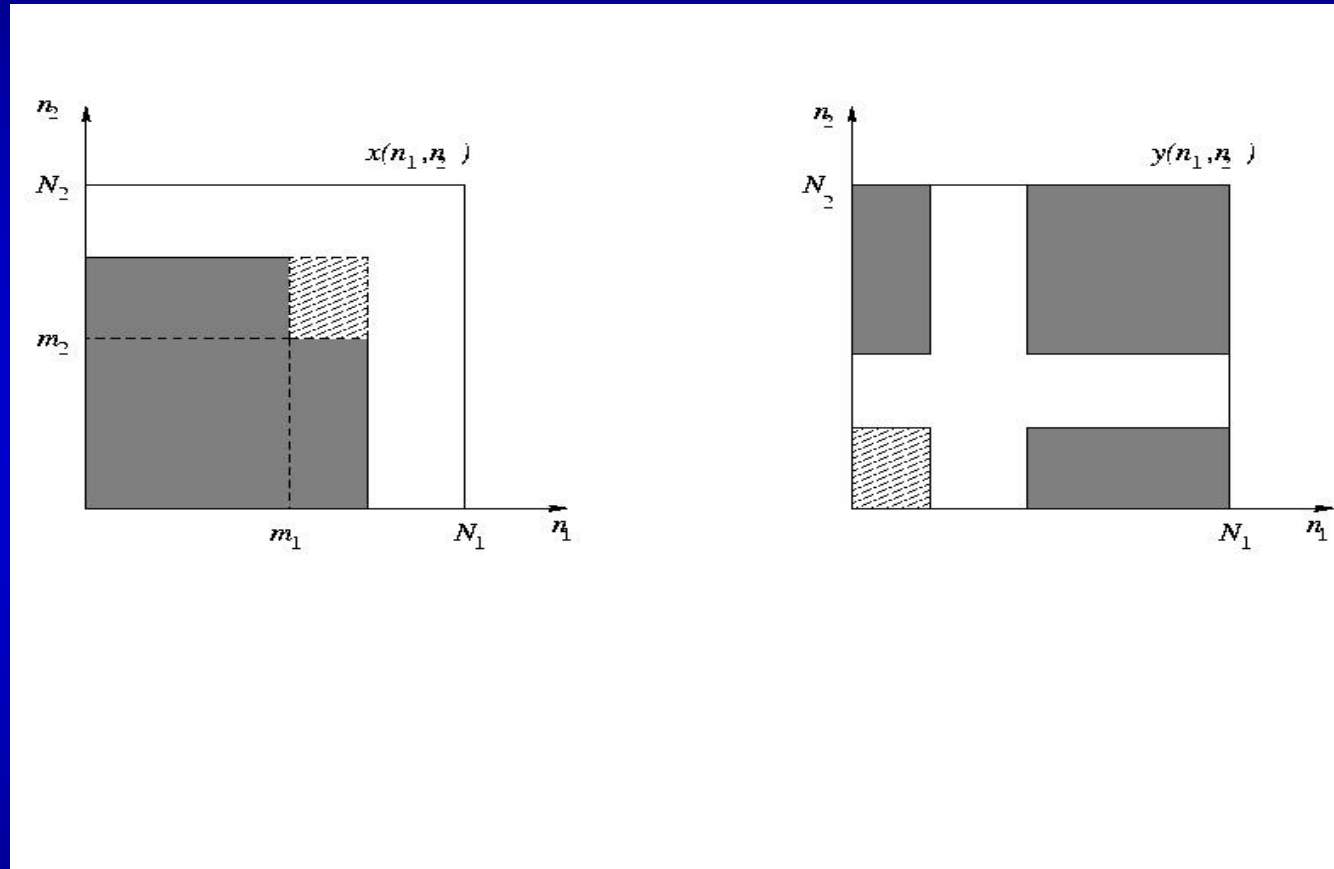


Figure 2: Circular shift of a 2-d sequence

## *Two-dimensional discrete Fourier transform*

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- ◆ In most applications the **linear convolution** of two signals is needed. It is defined as:

$$y(n_1, n_2) = \sum_{m_1=0}^{Q_1-1} \sum_{m_2=0}^{Q_2-1} h(m_1, m_2) x(n_1 - m_1, n_2 - m_2)$$

where  $R_{P_1P_2} = [0, P_1) \times [0, P_2)$  and  $R_{Q_1Q_2} = [0, Q_1) \times [0, Q_2)$  are the regions of support of  $x, h$ .

- ◆ The region of support of the convolution is:

$$R_{L_1L_2} = [0, L_1) \times [0, L_2) \quad L_i = P_i + Q_i - 1 \quad i = 1, 2$$

## *Two-dimensional discrete Fourier transform*

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◆ The algorithm consists of the following steps:

1. Choose  $N_1, N_2$  such that  $N_i \geq P_i + Q_i - 1, i = 1, 2$ .
2. Pad the sequences  $x(n_1, n_2)$  and  $h(n_1, n_2)$  with zeros, so that:

$$x_p(n_1, n_2) = \begin{cases} x(n_1, n_2) & (n_1, n_2) \in R_{P_1 P_2} \\ 0 & (n_1, n_2) \in R_{N_1 N_2} - R_{P_1 P_2} \end{cases}$$

$$h_p(n_1, n_2) = \begin{cases} h(n_1, n_2) & (n_1, n_2) \in R_{Q_1 Q_2} \\ 0 & (n_1, n_2) \in R_{N_1 N_2} - R_{Q_1 Q_2} \end{cases}$$

## *Two-dimensional discrete Fourier transform*

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3. Calculate the DFTs of the new sequences  $x_p(n_1, n_2)$  and  $h_p(n_1, n_2)$ .
4. Calculate the DFT  $Y_p(k_1, k_2)$ , as the product of  $X_p(k_1, k_2)$  and  $H_p(k_1, k_2)$ .
5. Calculate  $y_p(n_1, n_2)$  by using the inverse DFT. The result of the linear convolution is:

$$y(n_1, n_2) = y_p(n_1, n_2) \quad (n_1, n_2) \in R_{L_1 L_2}$$

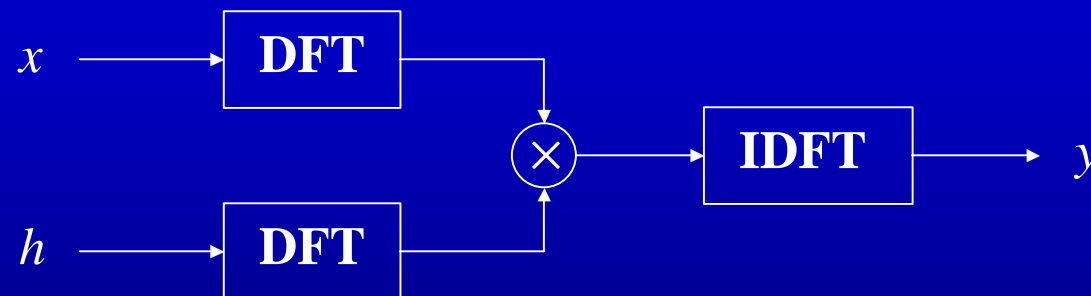


Figure 3: Convolution calculation using the DFTs

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## *Two-dimensional discrete Fourier transform*

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- ◆ The DFT also supports the **2-d correlation**:

$$R_{xy}(m_1, m_2) = \sum_{n_1=0}^{N_1-1} \sum_{n_2=0}^{N_2-1} x(n_1, n_2) y(n_1 + m_1, n_2 + m_2)$$

- ◆ If both sequences are real then in the frequency domain:

$$P_{xy}(k_1, k_2) = X^*(k_1, k_2) Y(k_1, k_2)$$

- ◆ The **autocorrelation** of an image is defined as:

$$R_{xx}(m_1, m_2) = \sum_{n_1=0}^{N_1-1} \sum_{n_2=0}^{N_2-1} x(n_1, n_2) x(n_1 + m_1, n_2 + m_2)$$

# *Two-dimensional discrete Fourier transform*

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## **Properties of the 2-d DFT**

### **1. Separable sequence:**

$$x(n_1, n_2) = x_1(n_1)x_2(n_2) \leftrightarrow X(k_1, k_2) = X_1(k_1)X_2(k_2)$$

### **2. Linearity:**

$$x(n_1, n_2) = a \cdot v(n_1, n_2) + b \cdot w(n_1, n_2) \leftrightarrow$$

$$X(k_1, k_2) = a \cdot V(k_1, k_2) + b \cdot W(k_1, k_2)$$

### **3. Circular shift:**

$$y(n_1, n_2) = x(((n_1 - m_1))_{N_1}, ((n_2 - m_2))_{N_2}) \leftrightarrow$$

$$Y(k_1, k_2) = W_{N_1}^{m_1 k_1} W_{N_2}^{m_2 k_2} X(k_1, k_2)$$



## *Two-dimensional discrete Fourier transform*

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### **4. Modulation:**

$$y(n_1, n_2) = W_{N_1}^{-n_1 l_1} W_{N_2}^{-n_2 l_2} x(n_1, n_2) \leftrightarrow$$
$$Y(k_1, k_2) = X(((k_1 - l_1))_{N_1}, ((k_2 - l_2))_{N_2})$$

### **5. Complex conjugate property:**

$$x^*((N_1 - n_1)_{N_1}, (N_2 - n_2)_{N_2}) \leftrightarrow X^*(k_1, k_2)$$

If  $x(n_1, n_2)$  is a real-valued signal:

$$X^*(k_1, k_2) = X((N_1 - k_1)_{N_1}, (N_2 - k_2)_{N_2})$$

### **6. Reflection:**

$$x(n_2, n_1) \leftrightarrow X(k_2, k_1)$$

## *Two-dimensional discrete Fourier transform*

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### **7. Initial value and DC value:**

$$x(0,0) = \frac{1}{N_1 N_2} \sum_{k_1=0}^{N_1-1} \sum_{k_2=0}^{N_2-1} X(k_1, k_2) \quad X(0,0) = \sum_{n_1=0}^{N_1-1} \sum_{n_2=0}^{N_2-1} x(n_1, n_2)$$

### **8. Parseval's theorem:**

$$\sum_{n_1=0}^{N_1-1} \sum_{n_2=0}^{N_2-1} x(n_1, n_2) y^*(n_1, n_2) = \frac{1}{N_1 N_2} \sum_{k_1=0}^{N_1-1} \sum_{k_2=0}^{N_2-1} X(k_1, k_2) Y^*(k_1, k_2)$$

$$\sum_{n_1=0}^{N_1-1} \sum_{n_2=0}^{N_2-1} |x(n_1, n_2)|^2 = \frac{1}{N_1 N_2} \sum_{k_1=0}^{N_1-1} \sum_{k_2=0}^{N_2-1} |X(k_1, k_2)|^2$$

### **9. Circular convolution and multiplication:**

$$x(n_1, n_2) \otimes \otimes h(n_1, n_2) \leftrightarrow X(k_1, k_2) \cdot H(k_1, k_2)$$

$$x(n_1, n_2) h(n_1, n_2) \leftrightarrow \frac{1}{N_1 N_2} X(k_1, k_2) \otimes \otimes H(k_1, k_2)$$

## *Row-column FFT algorithm*

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- ◆ The simplest algorithm for the calculation of the 2-d DFT is the Row - Column FFT (RCFFT) algorithm.
- ◆ The 2-d DFT can be decomposed in  $N_1$  DFTs along rows and  $N_2$  DFTs along columns:

$$X'(n_1, k_2) = \sum_{n_2=0}^{N_2-1} X(n_1, n_2) W_{N_2}^{n_2 k_2}$$

$$X(k_1, k_2) = \sum_{n_1=0}^{N_1-1} X'(n_1, k_2) W_{N_1}^{n_1 k_1}$$

## *Row-column FFT algorithm*

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- ◆ The transform magnitude is:

$$X_M(k_1, k_2) = \sqrt{X_R(k_1, k_2)^2 + X_I(k_1, k_2)^2}$$

- ◆ The transform phase is:

$$f(k_1, k_2) = \tan^{-1} \left( \frac{X_I(k_1, k_2)}{X_R(k_1, k_2)} \right)$$

- ◆ The magnitude of the transform provides useful information about the frequency content of an image.

## *Row-column FFT algorithm*

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- ◆ The number of complex multiplications for RCFFT is:

$$C = N_1 \frac{N_2}{2} \log_2 N_2 + N_2 \frac{N_1}{2} \log_2 N_1 = \frac{N_1 N_2}{2} \log_2 (N_1 N_2)$$

- ◆ If radix-2 FFT is used then the number of complex additions for RCFFT is:

$$A = N_1 N_2 \log_2 (N_1 N_2)$$

- ◆ The computational complexity is of the order :

$$O(kN^2 \log_2 N)$$

## *Memory problems in 2-d DFT calculations*

- ◆ There are memory problems in the calculation of 2-d DFT even for moderately sized images.
- ◆ A solution to this problem is the storage of the image on a hard disk in a row-wise manner.

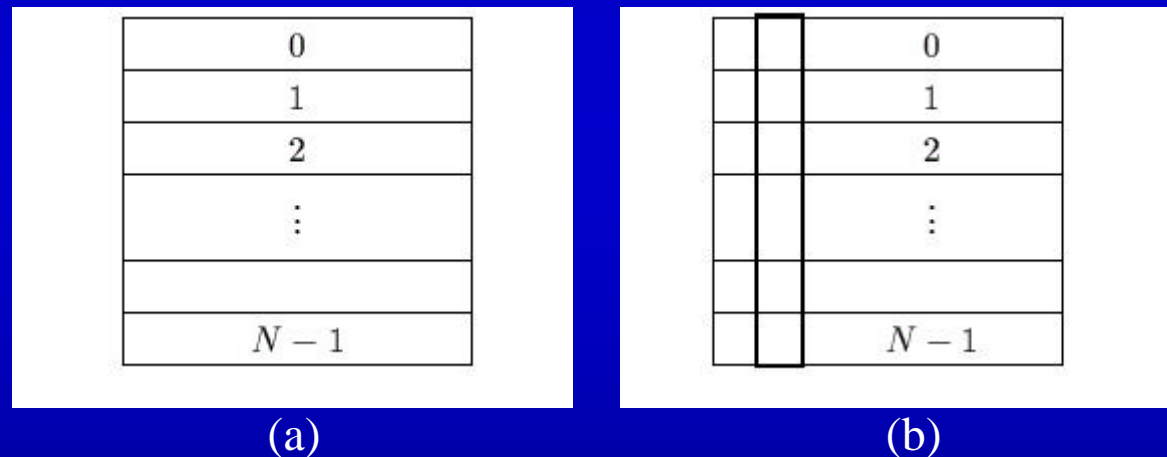


Figure 4: (a) Storage of an image in a row-wise manner. Each image row occupies one data record. b) Access of image in a column-wise manner.

## *Memory problems in 2-d DFT calculations*

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- ◆ The total number of I/O operations is:

$$N_{IO} = 2N + 3N + 2N(N-1) = 2N^2 + 3N$$

- ◆ If  $K$  signal rows (or columns) can be stored in RAM, the number of I/O operations required are:

$$N_{IO} = \frac{2N^2}{K} + 3N$$

## *Memory problems in 2-d DFT calculations*

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- ◆ A further speed-up is obtained by combining the row transform computation with a part of the column transform computation.
- ◆ The number of I/O operations is:

$$N_{IO} = 2N \lfloor n / k \rfloor$$



## *Memory problems in 2-d DFT calculations*

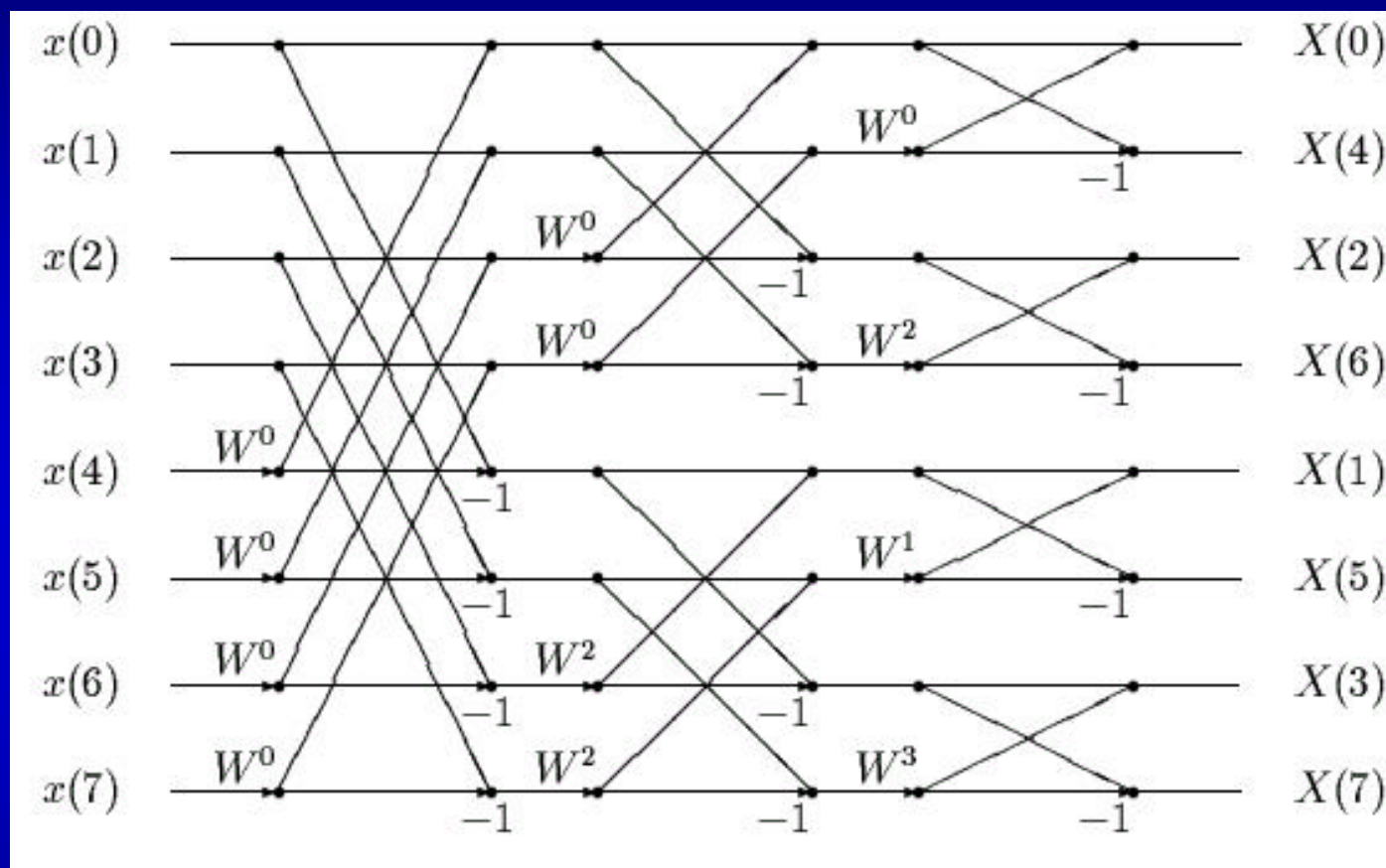


Figure 5: Radix-2 FFT algorithm for  $N=8$ .

## *Memory problems in 2-d DFT calculations*

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- ◆ Another approach for the reduction of the I/O operations is to use fast matrix transposition algorithms.
- ◆ If the matrix has size  $N \times N$ , where  $N = 2^n$ , it can be split into four submatrices of size  $(N/2) \times (N/2)$  each.
- ◆ This procedure is repeated until submatrices of size  $2 \times 2$  are reached.

## *Memory problems in 2-d DFT calculations*

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- ◆ This algorithm has  $n = \log_2 N$  steps.
- ◆ The transposition can be performed in place.
- ◆ The first stage needs  $2N$  I/O operations.
- ◆ The number of stages is  $\log_2 N$ .
- ◆ The total number of I/O operations is:

$$N_{IO} = 2N \log_2 N$$

# Memory problems in 2-d DFT calculations

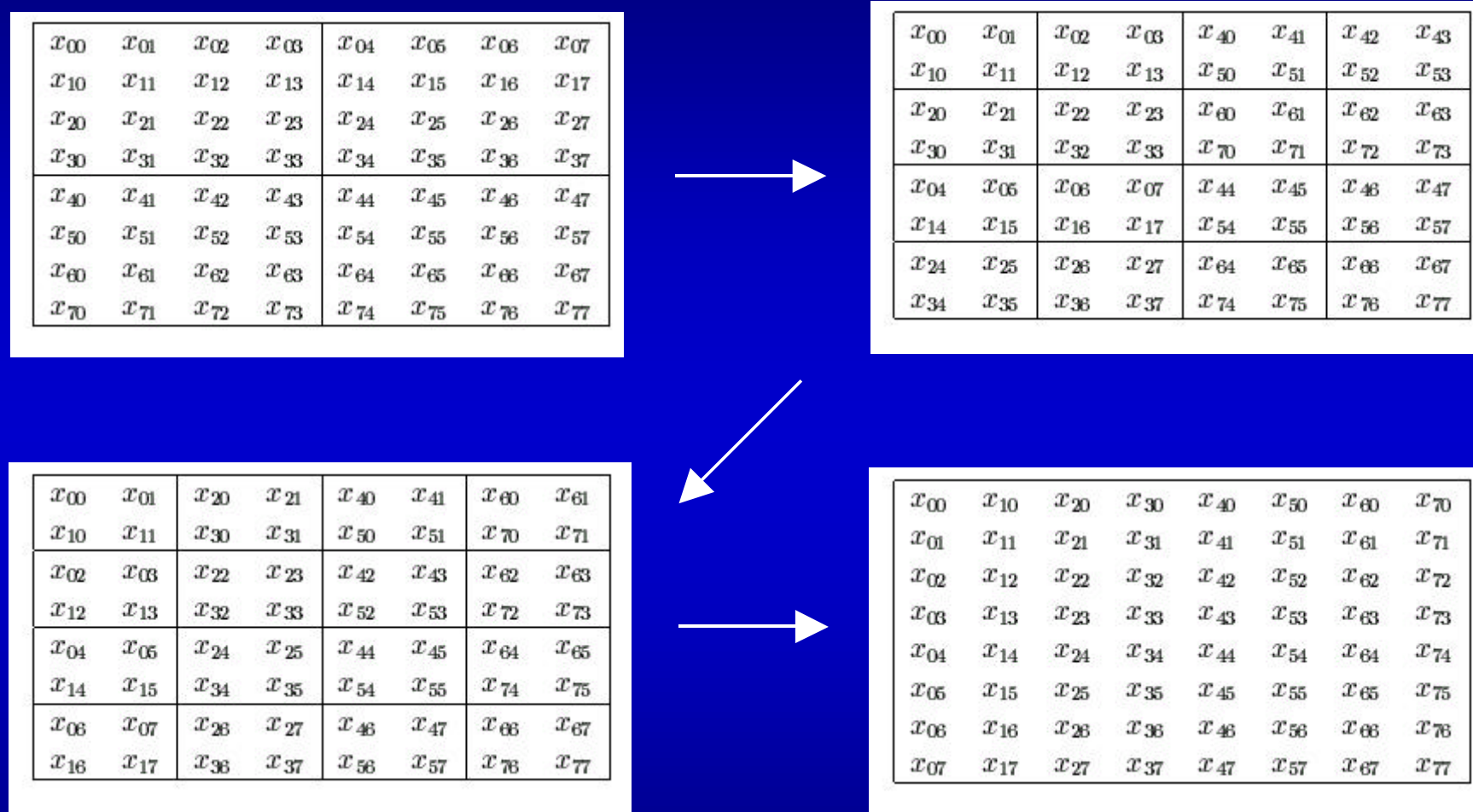


Figure 6: Three stages in the transposition of an 8x8 matrix.

## *Memory problems in 2-d DFT calculations*

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- ◆ If the image is real, the complex conjugate property can be used for reducing memory requirements.
- ◆ Suppose that the dimensions  $N_1$ ,  $N_2$  of the image are powers of 2 and that the image is stored on a matrix  $\mathbf{A}$  of size  $N_1 \times N_2$ .
- ◆ The first stage of the RFFT processes the conjugate symmetry.

## *Memory problems in 2-d DFT calculations*

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- ◆ The columns  $X'(n_1, 0)$ ,  $X'(n_1, N_2/2)$  are real numbers.
- ◆ They are used to store the real and imaginary parts of  $X'(n_1, k_2)$  in place as:

$$\begin{aligned} \text{Re}[X'(n_1, k_2)] &\longrightarrow \mathbf{A}(n_1, k_2) \\ \text{Im}[X'(n_1, k_2)] &\longrightarrow \mathbf{A}(n_1, N_2 - k_2) \end{aligned} \quad 1 \leq k_2 < N_2/2, 0 \leq n_1 \leq N_1 - 1$$

- ◆ This storage requires only 50% of the memory required for the storage of the complete complex signal and is performed in place.

## *Memory problems in 2-d DFT calculations*

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- ◆ The column transform also satisfies the conjugate property.
- ◆ The samples  $X(0, 0)$ ,  $X(N_1 / 2, 0)$ ,  $X(0, N_2 / 2)$ ,  $X(N_1 / 2, N_2 / 2)$  are real and can be stored in the corresponding positions of  $\mathbf{A}$ . The samples  $X(k_1, 0)$ ,  $X(k_1, N_2 / 2)$  can be stored as:

$$\text{Re}[X(k_1, 0)] \longrightarrow \mathbf{A}(k_1, 0)$$

$$\text{Im}[X(k_1, 0)] \longrightarrow \mathbf{A}(N_1 - k_1, 0)$$

$$\text{Re}[X(k_1, N_2 / 2)] \longrightarrow \mathbf{A}(k_1, N_2 / 2)$$

$$\text{Im}[X(k_1, N_2 / 2)] \longrightarrow \mathbf{A}(N_1 - k_1, N_2 / 2)$$

$$1 \leq k_1 < N_1 / 2$$

## *Memory problems in 2-d DFT calculations*

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- ◆ The real and imaginary parts of the samples  $X(k_1, k_2)$ ,  $1 \leq k_1 \leq N_1-1$ ,  $1 \leq k_2 < N_2/2$  are stored as:

$$\text{Re}[X(k_1, k_2)] \longrightarrow \mathbf{A}(k_1, k_2)$$

$$\text{Im}[X(k_1, k_2)] \longrightarrow \mathbf{A}(((N_1 - k_1))_{N_1}, ((N_2 - k_2))_{N_2})$$

$$\text{for } 1 \leq k_1 \leq N_1 - 1, \quad 1 \leq k_2 < N_2 / 2$$



## *Memory problems in 2-d DFT calculations*

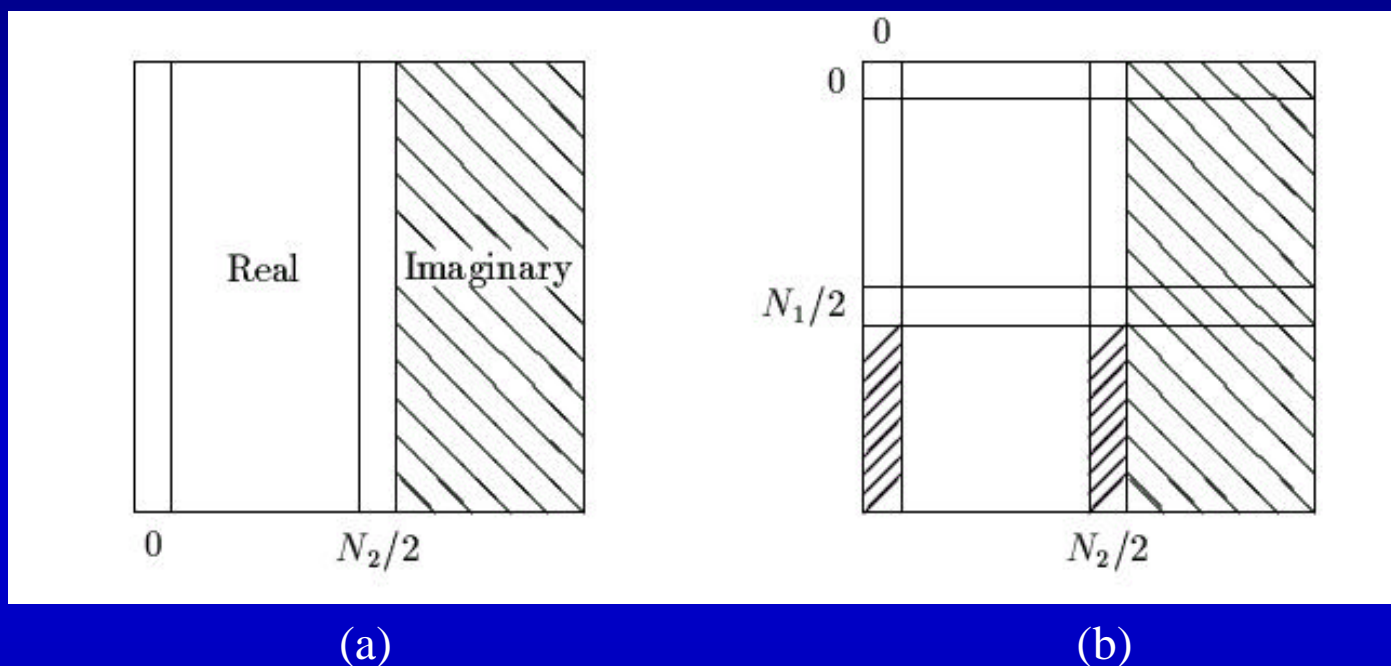


Figure 7: In-place storage of the 2-d DFT of a real-valued signal. (a) Storage after row transform. (b) Storage after column transform. The cross-hatched areas denote the storage places for the imaginary part of the transform.

## *Vector-radix fast Fourier transform algorithm*

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- ◆ Let  $x(n_1, n_2)$  be a square image  $N \times N$ .
- ◆ Its DFT can be split into four 2-d DFTs of size  $(N/2) \times (N/2)$ , by following a *decimation-in-time* approach:

$$\begin{aligned} X(k_1, k_2) &= \sum_{n_1=0}^{N-1} \sum_{n_2=0}^{N-1} x(n_1, n_2) W_N^{n_1 k_1} W_N^{n_2 k_2} \\ &= G_{ee}(k_1, k_2) + G_{eo}(k_1, k_2) W_N^{k_2} + \\ &\quad G_{oe}(k_1, k_2) W_N^{k_1} + G_{oo}(k_1, k_2) W_N^{k_1 + k_2} \end{aligned}$$

## *Vector-radix fast Fourier transform algorithm*

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Where:

$$S_{00}(k_1, k_2) = \sum_{l_1=0}^{N/2-1} \sum_{l_2=0}^{N/2-1} x(2l_1, 2l_2) W_N^{2l_1 k_1} W_N^{2l_2 k_2}$$

$$S_{01}(k_1, k_2) = \sum_{l_1=0}^{N/2-1} \sum_{l_2=0}^{N/2-1} x(2l_1, 2l_2 + 1) W_N^{2l_1 k_1} W_N^{2l_2 k_2}$$

$$S_{10}(k_1, k_2) = \sum_{l_1=0}^{N/2-1} \sum_{l_2=0}^{N/2-1} x(2l_1 + 1, 2l_2) W_N^{2l_1 k_1} W_N^{2l_2 k_2}$$

$$S_{11}(k_1, k_2) = \sum_{l_1=0}^{N/2-1} \sum_{l_2=0}^{N/2-1} x(2l_1 + 1, 2l_2 + 1) W_N^{2l_1 k_1} W_N^{2l_2 k_2}$$

## *Vector-radix fast Fourier transform algorithm*

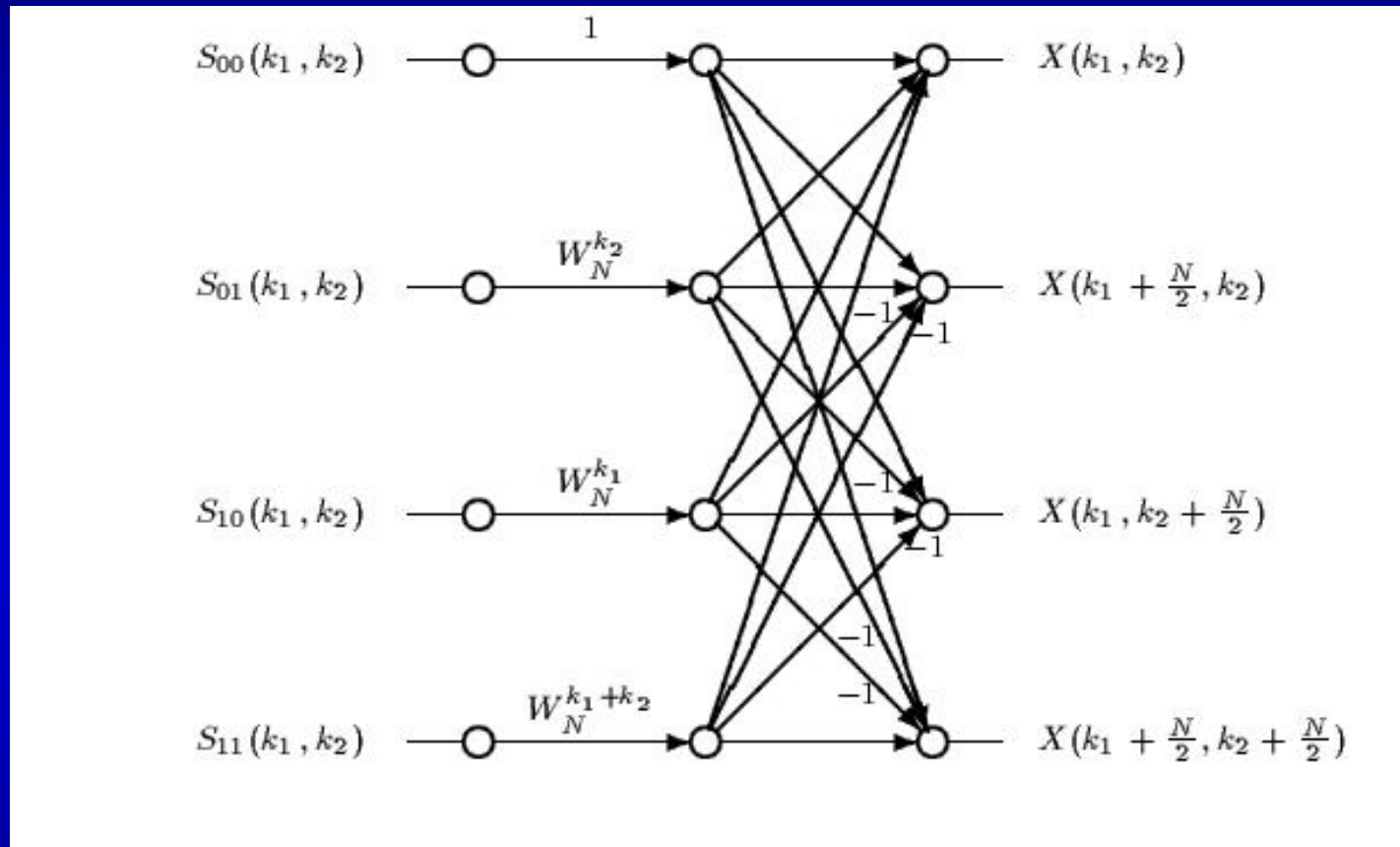


Figure 8: Radix-2x2 butterfly.

# Vector-radix fast Fourier transform algorithm

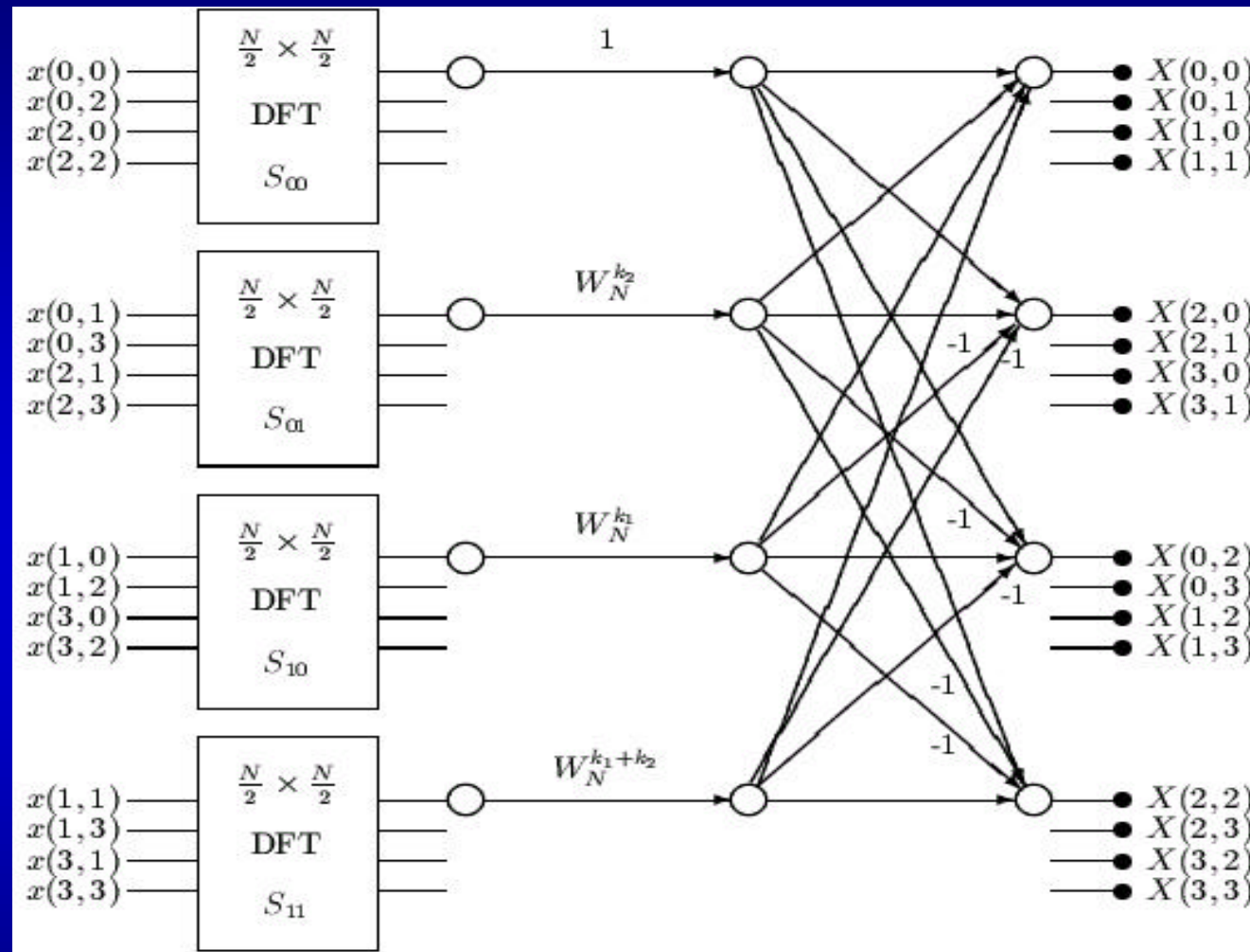


Figure 9: Flow diagram of a 4x4 vector-radix FFT.

## *Vector-radix fast Fourier transform algorithm*

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- ◆ VRFFT has  $\log_2 N$  stages.
- ◆ Each stage contains  $N^2/4$  butterflies.
- ◆ Each butterfly requires 3 complex multiplications.
- ◆ The total number of complex multiplications is:

$$C = \frac{3N^2}{4} \log_2 N$$

- ◆ The number of complex additions is:

$$A = 2N^2 \log_2 N$$

- ◆ All computations of the VRFFT can be performed in place.

## *Polynomial transform FFT*

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- ◆ A polynomial transform can be defined as:

$$\hat{X}_k(z) = \sum_{m=0}^{N-1} X_m(z) [G(z)]^{mk} \bmod P(z)$$

$$X_m(z) = \frac{1}{N} \sum_{k=0}^{N-1} \hat{X}_k(z) [G(z)]^{-mk} \bmod P(z)$$

where  $P(z)$  is an irreducible polynomial and

$$G(z) = 1 \bmod P(z)$$

is a polynomial  $N$ -th root of unity. The polynomial of degree  $N-1$  is:

$$X_m(z) = \sum_{n=0}^{N-1} x(m, n) z^n$$

## *Polynomial transform FFT*

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- ◆ The following polynomial transform is used for a 2-d FFT:

$$\hat{X}_k(z) = \sum_{m=0}^{N-1} X_m(z)(z^2)^{mk} \bmod (z^N + 1)$$

- ◆ Only  $2N^2 \log_2 N$  real additions are needed for the calculation of the polynomial transform.
- ◆ A polynomial transform can be employed for the fast calculation of the 2-d DFT.



## *Polynomial transform FFT*

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### ◆ Polynomial transform FFT (PTFFT).

$$X_{n_1}(z) = \sum_{n_2=0}^{N-1} x(n_1, n_2) W^{-n_2} z^{n_2}$$

$$\hat{X}_{(2k_2+1)k_1}(z) = \sum_{n_1=0}^{N-1} X_{n_1}(z) z^{2n_1k_1} \bmod(z^N + 1)$$

$$X((2k_2 + 1)k_1, k_2) = \sum_{l=0}^{N-1} y(k_1, l) W^l W^{2lk_2}$$

where  $y(k_1, l)$  are the coefficients of the polynomial:

$$\hat{X}_{(2k_2+1)k_1}(z) = \sum_{l=0}^{N-1} y(k_1, l) z^l$$

# Polynomial transform FFT

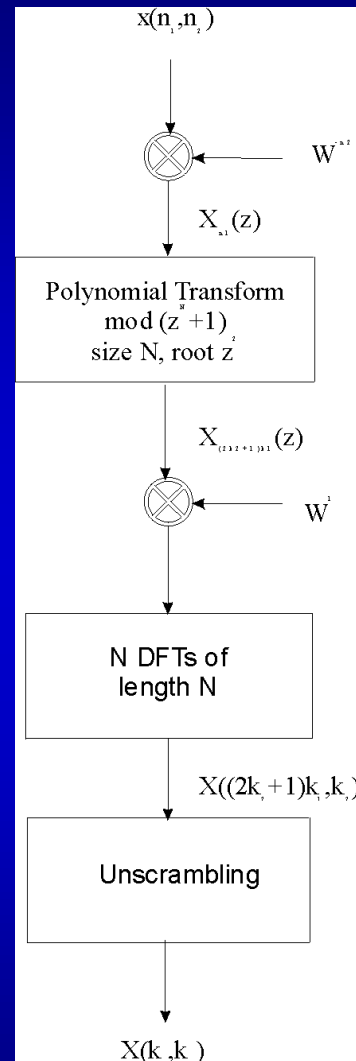


Figure 10: Polynomial transform FFT

## *Polynomial transform FFT*

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- ◆ If a radix-2 FFT is used for the 1-d DFTs then the total number of real multiplications is:

$$C = 2N^2(4 + \log_2 N)$$

- ◆ The total number of real additions is:

$$A = N^2(4 + 5\log_2 N)$$

- ◆ A comparison between RCFFT and PTFFT shows that PTFFT is better than RCFFT for  $N > 16$ .

## *Two dimensional power spectrum estimation*

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- ◆ The power spectrum carries important information about the 2-d signal content.
- ◆ The squared magnitude  $\hat{P}_{xx}(k_1, k_2)$  is the *periodogram* of the discrete signal and can be used as an estimator of its 2-d power spectrum.

$$\begin{aligned}\hat{P}_{xx}(k_1, k_2) &= \frac{1}{N_1 N_2} |X(k_1, k_2)|^2 \\ &= \frac{1}{N_1 N_2} \left| \sum_{n_1=0}^{N_1-1} \sum_{n_2=0}^{N_2-1} x(n_1, n_2) W_{N_1}^{n_1 k_1} W_{N_2}^{n_2 k_2} \right|^2\end{aligned}$$

## *Two dimensional power spectrum estimation*

---

- ◆ The periodogram  $\hat{P}_{xx}(\mathbf{w}_1, \mathbf{w}_2)$  is the Fourier transform of the estimator  $\hat{R}_{xx}(n_1, n_2)$  of the autocorrelation function:

$$\hat{R}_{xx}(n_1, n_2) = \frac{1}{(2N_1 + 1)(2N_2 + 1)} \sum_{k_1=-N_1}^{N_1} \sum_{k_2=-N_2}^{N_2} x^*(k_1, k_2) x(k_1 + n_1, k_2 + n_2)$$

- ◆ The periodogram is a smoothed version of the actual 2-d power spectrum. It is very poor for small images and it is a noisy power spectrum estimator.

## *Two dimensional power spectrum estimation*

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Figure 11: (a) Test image LENNA; (b) periodogram of LENNA.

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## *Two dimensional power spectrum estimation*

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- ◆ The *Bartlett* estimator can reduce the noise. The 2-d signal of size  $N_1 \times N_2$  is split into  $K_1 \times K_2$  non-overlapping sections each having size  $M_1 \times M_2$ :

$$x_{ij}(n_1, n_2) = x(n_1 + iM_1, n_2 + jM_2)$$

where  $i = 0, \dots, K_1 - 1$ ,  $j = 0, \dots, K_2 - 1$

- ◆ The periodogram of each section is:

$$\hat{P}_{xx}^{(ij)}(k_1, k_2) = \frac{1}{M_1 M_2} \left| \sum_{n_1=0}^{M_1-1} \sum_{n_2=0}^{M_2-1} x_{ij}(n_1, n_2) W_{M_1}^{n_1 k_1} W_{M_2}^{n_2 k_2} \right|^2$$

## *Two dimensional power spectrum estimation*

---

- ◆ The new spectral estimator is the average of the periodograms of all sections:

$$\hat{P}_{xx}^B(K_1, K_2) = \frac{1}{K_1 K_2} \sum_{i=0}^{K_1-1} \sum_{j=0}^{K_2-1} \hat{P}_{xx}^{(ij)}(k_1, k_2)$$

- ◆ *Blackman-Tukey* 2-d power spectrum estimator: An estimator of the 2-d autocorrelation function  $R_{xx}(m_1, m_2)$  is used:

$$P_{xx}^{BT}(k_1, k_2) = \sum_{m_1=0}^{2N_1-2} \sum_{m_2=0}^{2N_2-2} R_{xx}(m_1, m_2) w(m_1, m_2) W_{2N_1-1}^{m_1 k_1} W_{2N_2-1}^{m_2 k_2}$$



## *Two dimensional power spectrum estimation*

---

- ◆ A separable 2-d window can be used. The triangular 1-d window or the 1-d Hamming window can be used for each of the dimensions.
- ◆ The BT estimator can be obtained by using the 2-d DFT of the windowed autocorrelation function:

$$P_{xx}^{BT}(k_1, k_2) = DFT [w(m_1, m_2) R_{xx}(m_1, m_2)]$$

## *Two dimensional power spectrum estimation*

- ◆ Technique based on 2-d AR modeling of images.

$$x(n_1, n_2) = \sum_{(i,j) \in A} a(i, j) x(n_1 - i, n_2 - j) + w(n_1, n_2)$$

$A$  is the *prediction window*

$\hat{a}(i, j)$  are the *predictor coefficients*

$w(n_1, n_2)$  is a white noise random process, having variance  $\sigma_w^2$ .

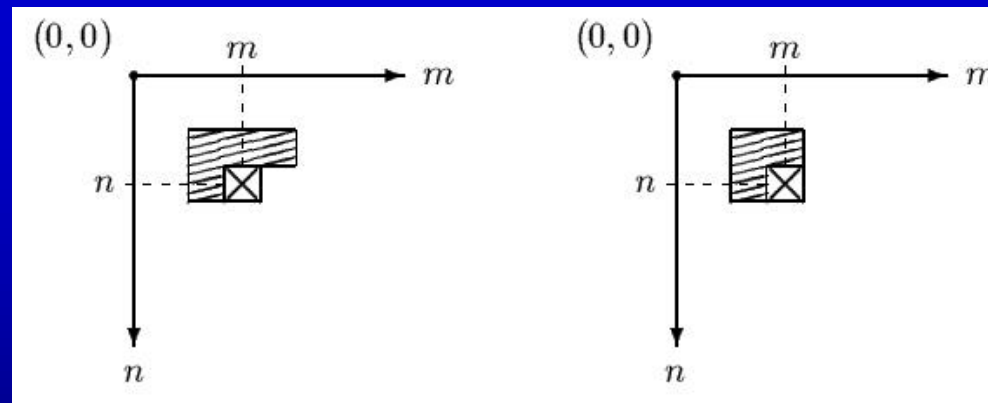


Figure 12: Examples of prediction windows.

## *Two dimensional power spectrum estimation*

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- ◆ The power spectrum can be estimated by the following formula:

$$P_{xx}^{AR}(k_1, k_2) = \frac{\mathbf{s}_w^2}{\left| \sum_{(m_1, m_2) \in A} \sum a(m_1, m_2) W_{N_1}^{m_1 k_1} W_{N_2}^{m_2 k_2} \right|^2}$$

## *Discrete cosine transform*

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- ◆ DCT is used in the JPEG and MPEG standards.

 Forward DCT transform:

$$C(0) = \frac{1}{\sqrt{N}} \sum_{n=0}^{N-1} x(n)$$

$$C(k) = \sqrt{\frac{2}{N}} \sum_{n=0}^{N-1} x(n) \cos \frac{(2n+1)kp}{2N}$$

 Inverse DCT:

$$x(n) = \frac{1}{\sqrt{N}} C(0) + \sqrt{\frac{2}{N}} \sum_{k=1}^{N-1} C(k) \cos \frac{(2n+1)kp}{2N}$$

## *Discrete cosine transform*

---

◆ Let  $x(n)$  be a signal. An *even sequence*  $f(n)$  can be produced by this signal as:

$$f(n) = \begin{cases} x(n) & 0 \leq n \leq N-1 \\ x(2N-1-n) & N \leq n \leq 2N-1 \end{cases}$$

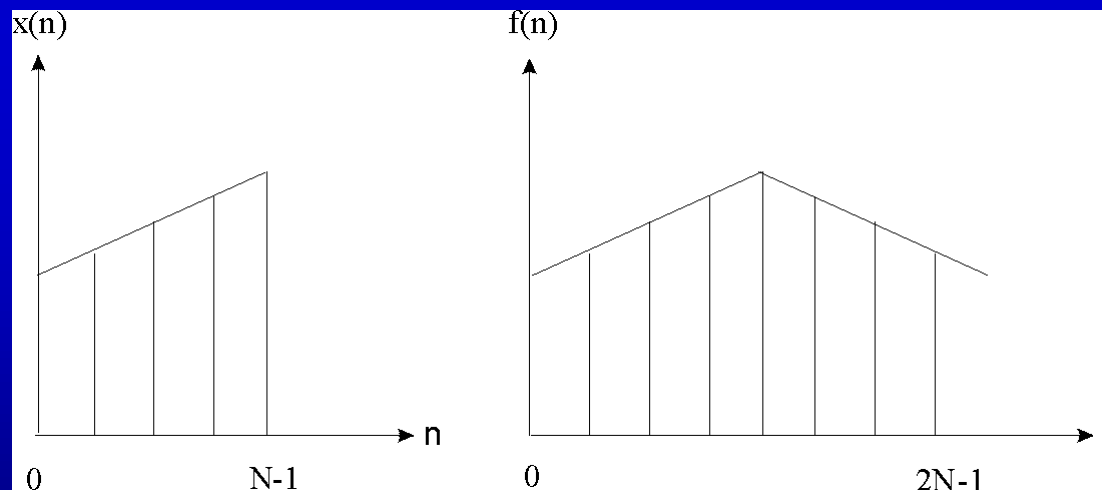


Figure 13: Creation of an even sequence

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## *Discrete cosine transform*

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### ◆ Algorithm for the fast calculation of DCT using DFT:

1. Formation of the even sequence  $f(n)$ .
2. The DFT of length  $2N$  is calculated by using a 1-d FFT of length  $2N$ .
3. Calculation of the DCT coefficients  $C(k)$  using the relations:

$$C(k) = \frac{W_{2N}^{k/2}}{\sqrt{2N}} F(k) \quad \text{for } 0 \leq k \leq N-1$$

where  $F(k)$  are the DFT coefficients.

## *Discrete cosine transform*

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- ◆ Alternative method for the fast calculation of the 1-d DCT:

$$C(k) = \sqrt{\frac{2}{N}} \sum_{n=0}^{N-1} x(n) \operatorname{Re} \left\{ \exp \left( -i \frac{(2n+1)kp}{2N} \right) \right\}$$

- ◆ If  $x(n)$  is a real sequence then:

$$C(k) = \sqrt{\frac{2}{N}} \operatorname{Re} \left\{ \exp \left( -i \frac{kp}{2N} \right) \sum_{n=0}^{2N-1} y(n) \exp \left( -i \frac{nkp}{N} \right) \right\}$$

where: 
$$y(n) = \begin{cases} x(n) & 0 \leq n \leq N-1 \\ 0 & N \leq n \leq 2N-1 \end{cases}$$

## *Discrete cosine transform*

---

- ◆ Alternative definition for the DCT pair:

$$C(k) = \sum_{n=0}^{N-1} 2x(n) \cos \frac{(2n+1)kp}{2N}$$

$$x(n) = \frac{1}{N} \sum_{k=0}^{N-1} w(k) C(k) \cos \frac{(2n+1)kp}{2N}$$

$$\text{where: } w(k) = \begin{cases} 1/2 & k=0 \\ 1 & 1 \leq k \leq N-1 \end{cases}$$

- ◆ Thus, the DCT coefficients are related to the DFT coefficients by:

$$C(k) = W_{2N}^{k/2} F(k)$$



## *Discrete cosine transform*

---

### ◆ Fast DCT algorithm:

1. Formation of a sequence  $\hat{i}(n)$  as:

$$v(n) = \begin{cases} x(2n) & 0 \leq n \leq \left\lfloor \frac{N-1}{2} \right\rfloor \\ x(2N-2n-1) & \left\lfloor \frac{N+1}{2} \right\rfloor \leq n \leq N-1 \end{cases}$$

2. Computation of the DFT  $V(k)$ ,  $0 \leq k \leq N-1$  by using an FFT algorithm of length  $N$ .

3. Computation of  $C(k)$ ,  $0 \leq k \leq [N/2]$ , and  $C(N-k)$  as:

$$C(k) = 2 \operatorname{Re} \left\{ W_{4N}^k \sum_{n=0}^{N-1} v(n) W_N^{nk} \right\} = 2 \operatorname{Re} \{ W_{4N}^k V(k) \}$$
$$C(N-k) = -2 \operatorname{Im} \{ W_{4N}^k V(k) \}$$

## *Discrete cosine transform*

---

### ◆ Fast calculation of the inverse DCT:

1. Computation of  $V(k)$  as:

$$V(k) = \frac{1}{2} W_{4N}^{-k} [C(k) - iC(N-k)] \quad 0 \leq k \leq N-1$$

2. Computation of  $\hat{v}(n)$  from  $V(k)$  by means of an inverse FFT algorithm of length  $N$ .

3. Retrieval of  $x(n)$  from  $\hat{v}(n)$  by using the formula:

$$v(n) = \begin{cases} x(2n) & 0 \leq n \leq \left\lfloor \frac{N-1}{2} \right\rfloor \\ x(2N-2n-1) & \left\lceil \frac{N+1}{2} \right\rceil \leq n \leq N-1 \end{cases}$$

## *Two-dimensional discrete cosine transform*

---

◆ A 2-d  $N_1 \times N_2$  DCT is defined as:

$$C(k_1, k_2) = \sum_{n_1=0}^{N_1-1} \sum_{n_2=0}^{N_2-1} 4x(n_1, n_2) \cos \frac{(2n_1+1)k_1 p}{2N_1} \cos \frac{(2n_2+1)k_2 p}{2N_2}$$

for  $0 \leq k_1 \leq N_1-1$ ,  $0 \leq k_2 \leq N_2-1$ .

$$x(n_1, n_2) = \frac{1}{N_1 N_2} \sum_{k_1=0}^{N_1-1} \sum_{k_2=0}^{N_2-1} w_1(k_1) w_2(k_2) C(k_1, k_2) \cos \frac{(2n_1+1)k_1 p}{2N_1} \cos \frac{(2n_2+1)k_2 p}{2N_2}$$

where:

$$w_1(k_1) = \begin{cases} 1/2 & k_1 = 0 \\ 1 & 1 \leq k_1 \leq N_1 - 1 \end{cases} \quad w_2(k_2) = \begin{cases} 1/2 & k_2 = 0 \\ 1 & 1 \leq k_2 \leq N_2 - 1 \end{cases}$$

## *Two-dimensional discrete cosine transform*

---

- ◆ The expansion of the signal forms a new one as:

$$f(n_1, n_2) = \begin{cases} x(n_1, n_2) & 0 \leq n_1 \leq N_1 - 1 & 0 \leq n_2 \leq N_2 - 1 \\ x(2N_1 - n_1 - 1, n_2) & N_1 \leq n_1 \leq 2N_1 - 1 & 0 \leq n_2 \leq N_2 - 1 \\ x(n_1, 2N_2 - n_2 - 1) & 0 \leq n_1 \leq N_1 - 1 & N_2 \leq n_2 \leq 2N_2 - 1 \\ x(2N_1 - n_1 - 1, 2N_2 - n_2 - 1) & N_1 \leq n_1 \leq 2N_1 - 1 & N_2 \leq n_2 \leq 2N_2 - 1 \end{cases}$$

- ◆ The DCT coefficients  $C(k_1, k_2)$  are related to the DFT ones  $F(k_1, k_2)$  as:

$$C(k_1, k_2) = W_{2N_1}^{k_1/2} W_{2N_2}^{k_2/2} F(k_1, k_2)$$

## *Two-dimensional discrete cosine transform*

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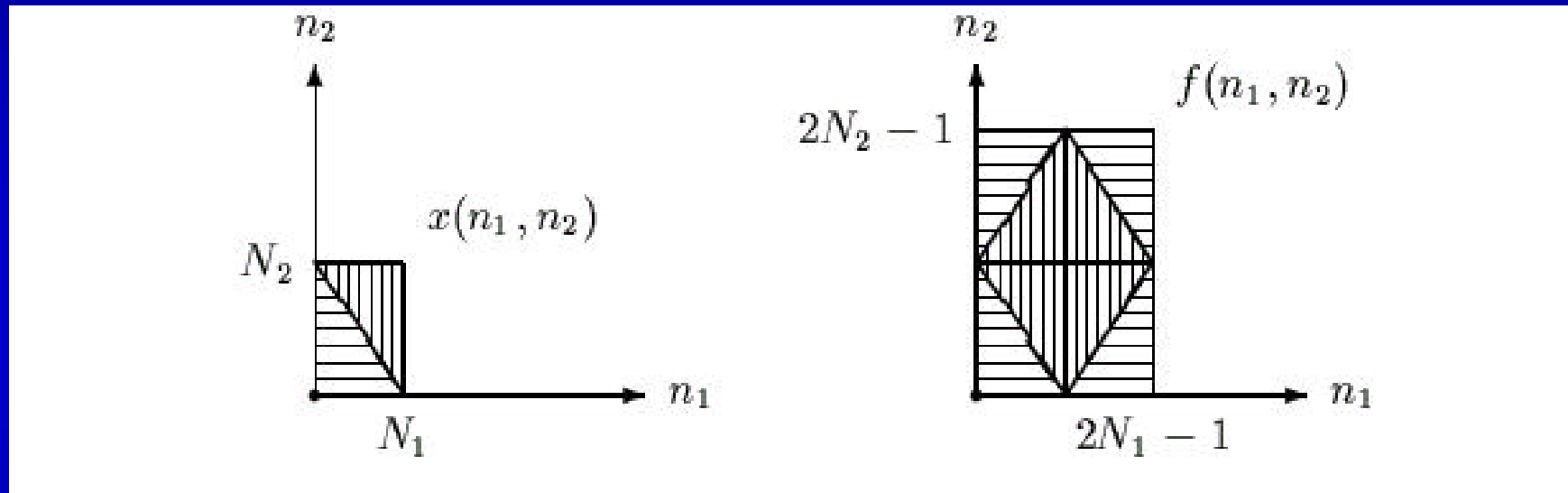


Figure 14: (a) Original sequence  $x(n_1, n_2)$ .  
(b) Expanded sequence  $f(n_1, n_2)$ .

## *Two-dimensional discrete cosine transform*

---

- ◆ Fast calculation of the 2-d DCT follows:

1. Formation of a sequence  $\acute{i}(n_1, n_2)$  as:

$$v(n_1, n_2) = \begin{cases} x(2n_1, 2n_2) \\ x(2N_1 - 2n_1 - 1, 2n_2) \\ x(2n_1, 2N_2 - 2n_2 - 1) \\ x(2N_1 - 2n_1 - 1, 2N_2 - 2n_2 - 1) \end{cases}$$

for:

$$\begin{aligned} &0 \leq n_1 \leq \left\lfloor \frac{N_1 - 1}{2} \right\rfloor & 0 \leq n_2 \leq \left\lfloor \frac{N_2 - 1}{2} \right\rfloor \\ &\left\lfloor \frac{N_1 + 1}{2} \right\rfloor \leq n_1 \leq N_1 - 1 & 0 \leq n_2 \leq \left\lfloor \frac{N_2 - 1}{2} \right\rfloor \\ &0 \leq n_1 \leq \left\lfloor \frac{N_1 - 1}{2} \right\rfloor & \left\lfloor \frac{N_2 + 1}{2} \right\rfloor \leq n_2 \leq N_2 - 1 \\ &\left\lfloor \frac{N_1 + 1}{2} \right\rfloor \leq n_1 \leq N_1 - 1 & \left\lfloor \frac{N_2 + 1}{2} \right\rfloor \leq n_2 \leq N_2 - 1 \end{aligned}$$

## *Two-dimensional discrete cosine transform*

---

2. The DFT  $V(k_1, k_2)$  is calculated by using a  $N_1 \times N_2$  FFT algorithm.

3. The DCT coefficients are calculated as:

$$\begin{aligned} C(k_1, k_2) &= 2 \operatorname{Re} \left\{ W_{4N_1}^{k_1} \left[ W_{4N_2}^{k_2} V(k_1, k_2) + W_{4N_2}^{-k_2} V(k_1, N_2 - k_2) \right] \right\} \\ &= 2 \operatorname{Re} \left\{ W_{4N_2}^{k_2} \left[ W_{4N_1}^{k_1} V(k_1, k_2) + W_{4N_1}^{-k_1} V(N_1 - k_1, k_2) \right] \right\} \end{aligned}$$

## *Two-dimensional discrete cosine transform*

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- ◆ There is also an algorithm for the fast calculation of the inverse 2-d DCT.

1. Computation of  $V(k_1, k_2)$  as:

$$V(k_1, k_2) = \frac{1}{4} W_{4N_1}^{-k_1} W_{4N_2}^{-k_2} \{ [C(k_1, k_2) - C(N_1 - k_1, N_2 - k_2)] \\ - i [C(N_1 - k_1, k_2) + C(k_1, N_2 - k_2)] \}$$

2. Calculation of  $i(n_1, n_2)$  by using an inverse  $N_1 \times N_2$  2-d FFT algorithm.



## *Two-dimensional discrete cosine transform*

---

3. Retrieval of  $x(n_1, n_2)$  from  $i(n_1, n_2)$  by using the following formula:

$$v(n_1, n_2) = \begin{cases} x(2n_1, 2n_2) \\ x(2N_1 - 2n_1 - 1, 2n_2) \\ x(2n_1, 2N_2 - 2n_2 - 1) \\ x(2N_1 - 2n_1 - 1, 2N_2 - 2n_2 - 1) \end{cases}$$

for:

$$\begin{aligned} &0 \leq n_1 \leq \left\lfloor \frac{N_1 - 1}{2} \right\rfloor & 0 \leq n_2 \leq \left\lfloor \frac{N_2 - 1}{2} \right\rfloor \\ &\left\lceil \frac{N_1 + 1}{2} \right\rceil \leq n_1 \leq N_1 - 1 & 0 \leq n_2 \leq \left\lfloor \frac{N_2 - 1}{2} \right\rfloor \\ &0 \leq n_1 \leq \left\lfloor \frac{N_1 - 1}{2} \right\rfloor & \left\lceil \frac{N_2 + 1}{2} \right\rceil \leq n_2 \leq N_2 - 1 \\ &\left\lceil \frac{N_1 + 1}{2} \right\rceil \leq n_1 \leq N_1 - 1 & \left\lceil \frac{N_2 + 1}{2} \right\rceil \leq n_2 \leq N_2 - 1 \end{aligned}$$

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