

Graphs and Network Flows

IE411

Lecture 2

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References for Today's Lecture

- Required reading
 - Sections 17.2-17.5
- References
 - AMO [Sections 2.3](#)
 - CLRS [Section 22.1](#)

Network Representation

- Our goal is to develop “efficient” algorithms → reasonable computation time.
- The main factors affecting efficiency are
 - The underlying algorithm
 - Data structure for storing the network
- The same algorithm may behave much differently with different graph data structure.
- What information do we need to store?
 - network topology (structure of nodes and arcs)
 - associated data (costs, capacities, supplies/demands)
- What are the important operations we might need to perform with a network data structure?

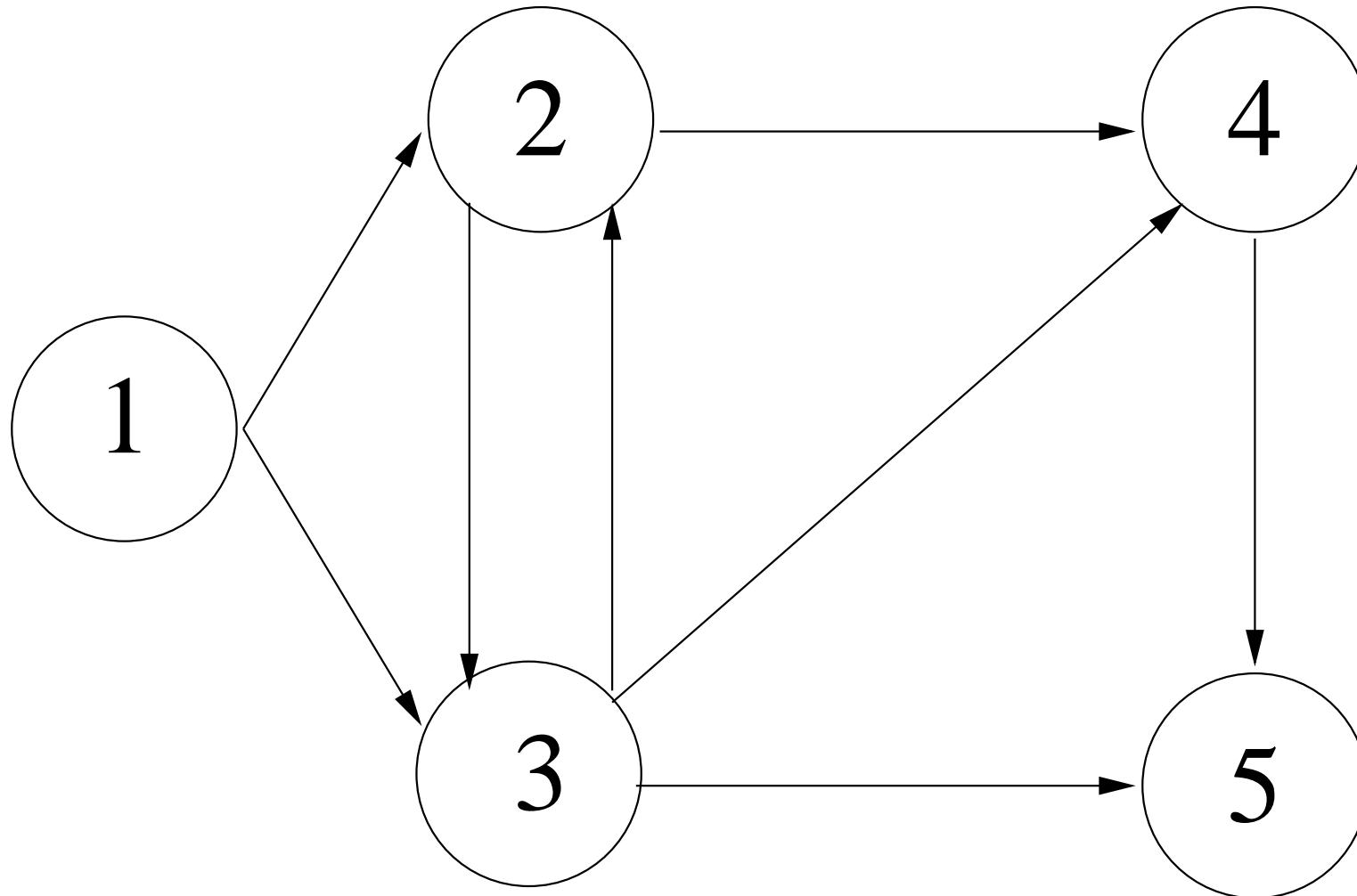
Common Representations

- Data structures
 - Node-Arc Incidence Matrix
 - Node-Node Adjacency Matrix
 - Adjacency List
 - Forward Star (Reverse Star)
- How do we evaluate a data structure?

Aside: Multiarcs and Loops

- *Multiarcs* are two or more arcs with the same tail and head nodes.
- A *loop* is an arc with the property that its tail and head nodes are the same.
- Generally we will assume that our networks do not contain parallel arcs or loops.
- The existence of such arcs can cause problems with standard data structures.

Example Graph



(Node-Arc) Incidence Matrix

- $n \times m$ matrix denoted \mathcal{N} .
- One row for each node and one column for each arc.
- For each arc (i, j) , put $+1$ in row i and -1 in row j .

	(1, 2)	(1, 3)	(2, 3)	(2, 4)	(3, 2)	(3, 4)	(3, 5)	(4, 5)
1								
2								
3								
4								
5								

(Node-Arc) Incidence Matrix

- What is the size of the matrix?
- How many entries are non-zero?
- What information do we get by reading across a row?
- Is this a space efficient representation?
- How about other operations?

(Node-Node) Adjacency Matrix

- $n \times n$ matrix denoted \mathcal{H}
- one row for each node and one column for each node
- entry $h_{ij} = 1$ if arc $(i, j) \in A$ (0 otherwise)

	1	2	3	4	5
1					
2					
3					
4					
5					

(Node-Node) Adjacency Matrix

- What is the size of the matrix?
- How many entries are non-zero?
- What data structures might we use to store arc costs and capacities?
- Is this a space efficient representation?
- What operations are most efficient with this data structure?

Adjacency List

- Adjacency list of node i , $A(i)$, is a list of the nodes j for which $(i, j) \in A$
- List stored as a *linked list*.
- Need one linked list of length $|A(i)|$ for each node.
- Cell can store additional fields such as arc cost and capacity
- Is this a space efficient representation?
- What operations are most efficient with this data structure?

Forward Star

- Stores node adjacency list of each node in one large array
- Associates a unique sequence number with each arc using a specific order starting with arcs outgoing from node 1, then node 2, etc.
- Stores tail information about each arc in **tail** array, head information in **head** array, etc.
- Maintains a pointer for each node that indicates the smallest numbered arc in the arc list for that node.
- For consistency, set $\text{pointer}(1)$ to 1 and $\text{pointer}(n + 1)$ to $m + 1$.
- What are the advantages of this representation?

Reverse Star

- Similar to a forward start except that arcs are sequenced starting with arcs incoming from node 1.
- The two representations can be maintained side-by-side if necessary.

Miscellaneous Issues

- Parallel Arcs
 - Why would we need parallel arcs?
 - Which representation(s) could accommodate them?
- Undirected Network
 - What needs to change?
 - * Node-Arc Incidence Matrix
 - * Node-Node Adjacency Matrix
 - * Adjacency List
 - What needs to happen when we update (i, j) ?

Summary of Representations

Representation	Storage Space	Features
Incidence Matrix	nm	<ol style="list-style-type: none"> 1. Space inefficient 2. Expensive to manipulate 3. MCFP constraint matrix
Adjacency Matrix	kn^2	<ol style="list-style-type: none"> 1. Suited to dense networks 2. Easy to implement
Adjacency List	$k_1n + k_2m$	<ol style="list-style-type: none"> 1. Space efficient 2. Efficient to manipulate 3. Suited to dense and sparse
Forward Star	$k_3n + k_4m$	<ol style="list-style-type: none"> 1. Space efficient 2. Efficient to manipulate 3. Suited to dense and spare

Table 1: From Ahuja et al. Figure 2.25