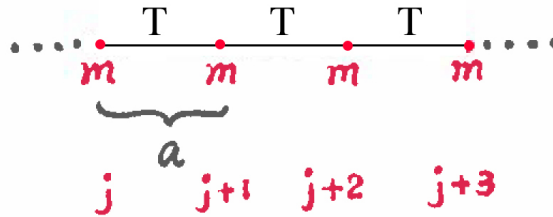


## 8.03 Lecture 16

We have discussed this system in lecture 8:



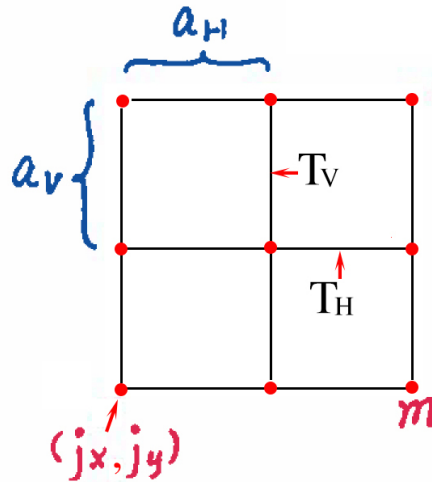
Mass can only move up and down in the  $\hat{y}$  direction. We have solved it by “space translation symmetry.” We obtained the dispersion relation:

$$\omega(k) = \frac{T}{ma} \sin\left(\frac{ka}{2}\right)$$

Where  $T$  is string tension,  $m$  is mass,  $a$  is the distance between masses at equilibrium. Eigenvectors (where  $j$  is the label of the mass):

$$e^{ikj \cdot a}$$

Today we are doing 2D and 3D system!! In general, we don't know how to solve those systems! :( But we know how to solve highly symmetric systems!! If we consider an infinitely long array of masses:



Where  $m$  is the mass,  $T_V, T_H$  are the tensions, and we have ideal strings. Particles can only move in the  $\hat{z}$  direction. Good news: space translation symmetry! Eigenvectors:

$$e^{ik_x x} e^{ik_y y}$$

Where  $x \equiv j_x a_H$  and  $y = j_y a_V$  and  $(j_x, j_y)$  are indices.

$$\Rightarrow \psi(x, y) = A e^{ik_x x} e^{ik_y y} = A e^{i\vec{k} \cdot \vec{r}}$$

We can use the expression above to get the dispersion relation:

$$\omega^2 = \frac{4T_H}{ma_h} \sin^2\left(\frac{k_x a_H}{2}\right) + \frac{4T_V}{ma_V} \sin^2\left(\frac{k_y a_V}{2}\right)$$

This is a dispersive medium because  $\frac{\omega}{|k|}$  is not a constant.

At fixed  $\omega$ : If we consider a 1D bead-string system:



There are two solutions (or eigenvectors of  $S$  matrix) which gives angular frequency  $\omega$

$$e^{ikx} \text{ and } e^{-ikx}$$

This is  $\cos(kx)$  and  $\sin(kx)$ !!

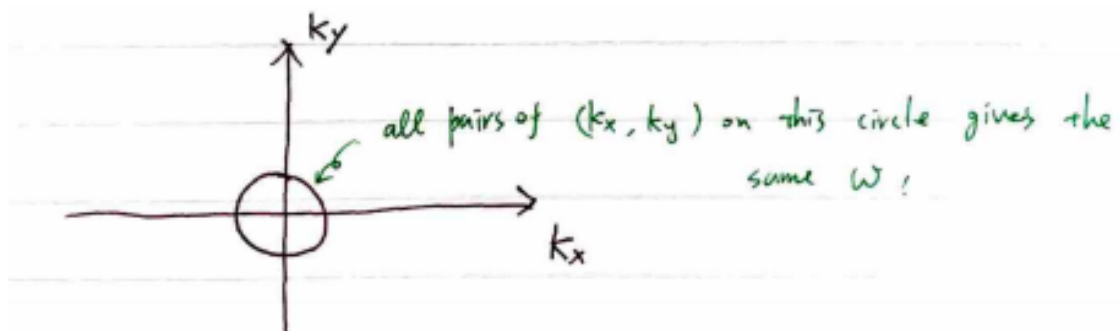
$$\cos(kx) = \frac{1}{2}(e^{ikx} + e^{-ikx})$$

$$\sin(kx) = \frac{1}{2i}(e^{ikx} - e^{-ikx})$$

We know from the discussion above, the eigenvector of  $M^{-1}k$  matrix is  $\sin$  or  $\cos$ . Back to the two-dimensional case: If we fix the angular frequency to be  $\omega$ . There are multiple values of  $k_x$  and  $k_y$  which can give the same  $\omega$  (actually infinite number of choices). This is because  $k_x$  and  $k_y$  are continuous: can be any value before we introduce boundary conditions. If we lower  $k_x$  a bit we can increase  $k_y$  to compensate! Example: if I have dispersion relation of this form:

$$\omega^2 = 5 \sin^2 k_x + 5 \sin^2 k_y$$

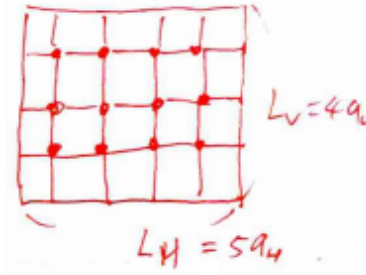
There are many possible pairs of  $k_x$  and  $k_y$  which gives the same  $\omega$ !!!



Now we add the wall back in:

$$\psi(0, y, t) = \psi(L_H, y, t) = \psi(x, 0, t) = \psi(x, L_V, t) = 0$$

In this example:  $L_H = 5a_H$  and  $L_V = 4a_V$



There are now only four modes of the finite system with the same  $\omega$

$$Ae^{\pm ik_x x} e^{\pm ik_y y}$$

$$k_x = \frac{n_x \pi}{L_H} \quad k_y = \frac{n_y \pi}{L_V}$$

$$L_H = 5a_H \quad L_V = 4a_V$$

and  $n_x$  runs from 1 to 4 while  $n_y$  runs from 1 to 3. Linear combinations of

$$e^{+ik_x x} e^{+ik_y y}, e^{+ik_x x} e^{-ik_y y}, e^{-ik_x x} e^{+ik_y y}, e^{-ik_x x} e^{-ik_y y}$$

gives  $A \sin k_x x \sin k_y y$  which satisfy the boundary conditions.

$$\Rightarrow \psi_{(n_x, n_y)}(x, y, t) = A_{(n_x, n_y)} \sin\left(\frac{n_x \pi x}{L_H}\right) \sin\left(\frac{n_y \pi y}{L_V}\right)$$

Discrete case general solution:

$$\psi(x, y, t) = \sum_{n_x, n_y} A_{(n_x, n_y)} \sin\left(\frac{n_x \pi x}{L_H}\right) \sin\left(\frac{n_y \pi y}{L_V}\right)$$

Continuous case (assuming  $T_H = T_V = T$ )  $a_H = a_V \rightarrow 0$

$$\omega^2 = \frac{4T}{ma} \frac{k_x^2 a^2}{4} + \frac{4T}{ma} \frac{k_y^2 a^2}{4}$$

$$= \frac{Ta}{m} (k_x^2 + k_y^2)$$

Define the surface mass density,  $\rho = m/a^2$ , and the surface tension,  $T_s = T/a$

$$\omega^2 = \frac{T_s}{\rho_s} (k_x^2 + k_y^2) = \frac{T_s}{\rho_s} |\vec{k}|^2$$

Similar to one dimensional case. Continuous limit gives:

$$\frac{\partial^2}{\partial t^2} \psi(x, y, t) = v^2 \left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \psi(x, y, t)$$

$$= v^2 \nabla^2 \psi(x, y, t)$$

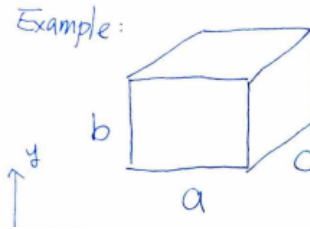
$$\Rightarrow \frac{\partial^2}{\partial t^2} \psi(x, y, t) = v^2 \nabla^2 \psi(x, y, t)$$

$$\psi \propto A \sin(k_x x) \sin(k_y y) \sin(\omega t + \phi)$$

Where  $v = \sqrt{T_s/\rho_s}$ . Similarly in the 3D case:

$$\frac{\partial^2}{\partial t^2} \psi(x, y, z, t) = v^2 \nabla^2 \psi(x, y, z, t)$$

Continuous case: 3D sound wave. Example: sound wave in a box



$$k_x = \frac{n_x \pi}{a} \quad k_y = \frac{n_y \pi}{b} \quad k_z = \frac{n_z \pi}{c}$$

Guess

$$\vec{\psi} \propto \sin(k_x x) \sin(k_y y) \sin(k_z z) \sin(\omega t + \phi)$$

Plug into wave equation:

$$\begin{aligned} \omega^2 &= v^2 (k_x^2 + k_y^2 + k_z^2) \\ &= v^2 \left( \left( \frac{n_x \pi}{a} \right)^2 + \left( \frac{n_y \pi}{b} \right)^2 + \left( \frac{n_z \pi}{c} \right)^2 \right) \end{aligned}$$

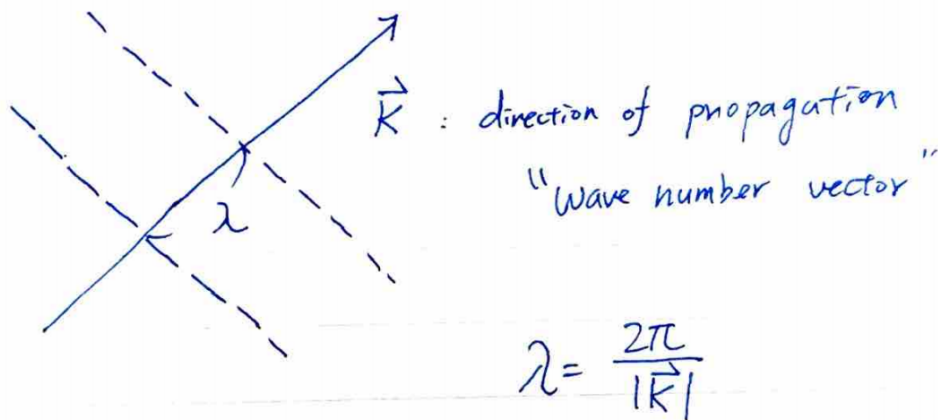
Where  $n_x, n_y$ , and  $n_z$  are integers.

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2 and 3D progressive wave:

Simple example: "plane waves"

$$\psi(\vec{r}, t) = A e^{i(\vec{k} \cdot \vec{r} - \omega t)}$$

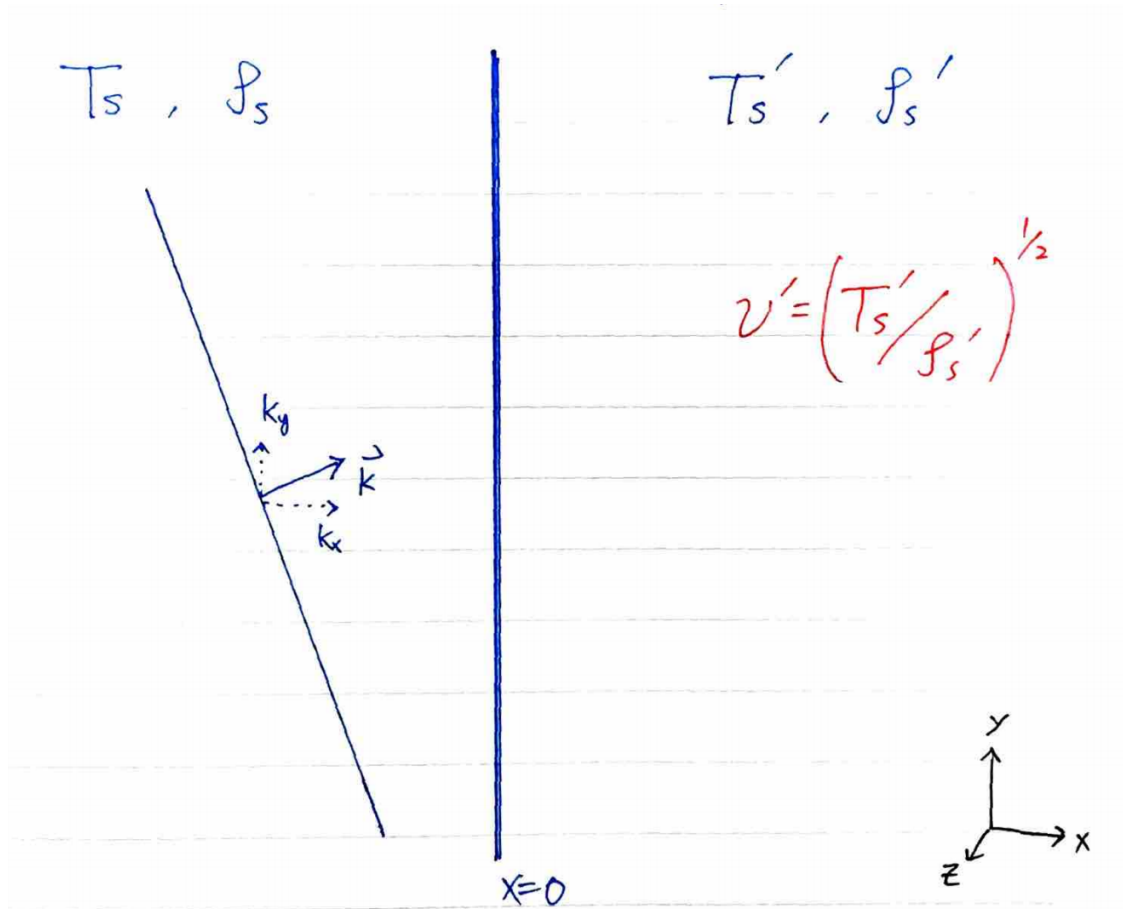


This can be used to describe EM waves, sound waves, or waves on membranes. If there is no other medium, this wave will continue forever.

Let's continue a 2D membrane stretched in the  $z = 0$  plane with surface mass density  $\rho_s$  and surface tension  $T_s$

$$\omega^2 = v^2(k_x^2 + k_y^2)$$

and waves will travel at speed  $v = \sqrt{\frac{T_s}{\rho_s}}$ . To add some excitement:



We place a second membrane on the other side, and our wave approaches this membrane. What will happen? One would usually expect an incident wave to produce a reflected and transmitted wave.

$$\psi_L = \underbrace{A e^{i(\vec{k} \cdot \vec{r} - \omega t)}}_{\text{Incident}} + \sum_{\alpha} R_{\alpha} \underbrace{A e^{i(\vec{k}_{\alpha} \cdot \vec{r} - \omega t)}}_{\text{Reflected}} \quad (x \leq 0)$$

$$\psi_R = \sum_{\beta} T_{\beta} \underbrace{A e^{i(\vec{k}_{\beta} \cdot \vec{r} - \omega t)}}_{\text{Transmitted}} \quad (x \geq 0)$$

Where  $\sum_{\alpha}$  and  $\sum_{\beta}$  sum over all possible  $\vec{k}_{\alpha}$  and  $\vec{k}_{\beta}$  which give angular frequency  $\omega$

$$|k_{\alpha}|^2 = \omega^2 \frac{\rho_s}{T_s} = \frac{\omega^2}{v^2} \quad , \quad |k_{\beta}|^2 = \omega^2 \frac{\rho'_s}{T'_s} = \frac{\omega^2}{v'^2}$$

To calculate  $R_{\alpha}$  and  $T_{\beta}$  as well as  $\vec{k}_{\alpha}$  and  $\vec{k}_{\beta}$  we need boundary conditions!

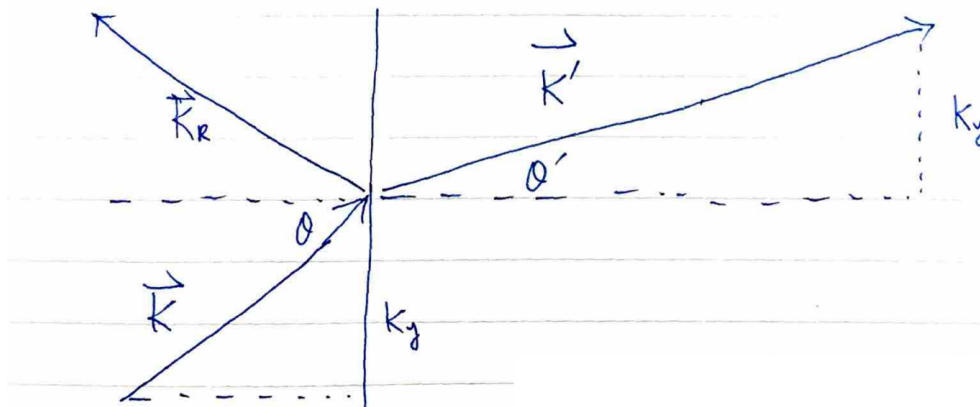
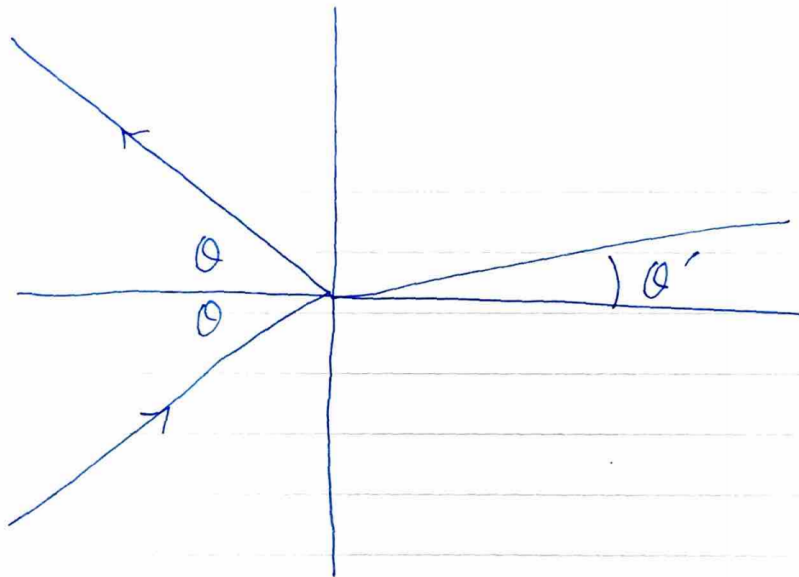
At  $x = z = 0$  the membrane cannot break so we need  $\psi_L = \psi_R$

$$\psi(0, y, 0, t) = Ae^{i(k_y y - \omega t)} + \sum_{\alpha} R_{\alpha} Ae^{i(k_{\alpha y} y - \omega t)} = \sum_{\beta} T_{\beta} Ae^{i(k_{\beta y} y - \omega t)}$$

Where the equality is established with the boundary condition. This can only be true when  $k_{\alpha y} = k_{\beta y} = k_y$ . Only when

$$k_{\alpha x} = -\sqrt{\omega^2/v^2 - k_y^2} = -k_x \quad \text{and} \quad k_{\beta x} = \sqrt{\omega^2/v'^2 - k_y^2}$$

We can satisfy the boundary condition.

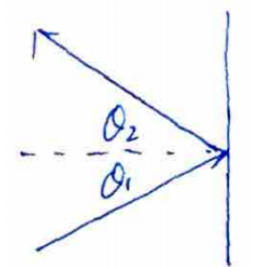


We have  $|\vec{k}| \sin \theta = |\vec{k}'| \sin \theta'$

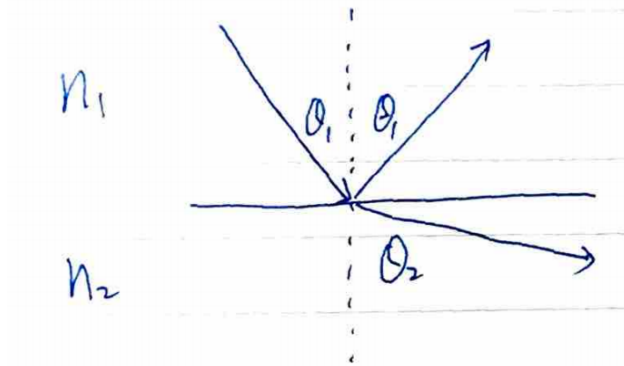
$$\begin{aligned}n &= \frac{c}{v} = \frac{c}{\omega} |k| \\n' &= \frac{c}{v'} = \frac{c}{\omega} |\vec{k}'| \\ \Rightarrow n \sin \theta &= n' \sin \theta'\end{aligned}$$

Snell's Law! We have just proved the two MOST IMPORTANT LAWS of geometrical optics!!!

(1.) Reflection:  $\theta_1 = \theta_2$



(2.) Snell's Law:  $n_1 \sin \theta_1 = n_2 \sin \theta_2$  where  $n$  is a refraction index



(3.) It works for water, glass, sound, and light waves!

(4.) If we continue to increase  $\theta_1$  then

$$\frac{n_1}{n_2} \sin \theta_1 > 1$$

There is no transmission!

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Fall 2016

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